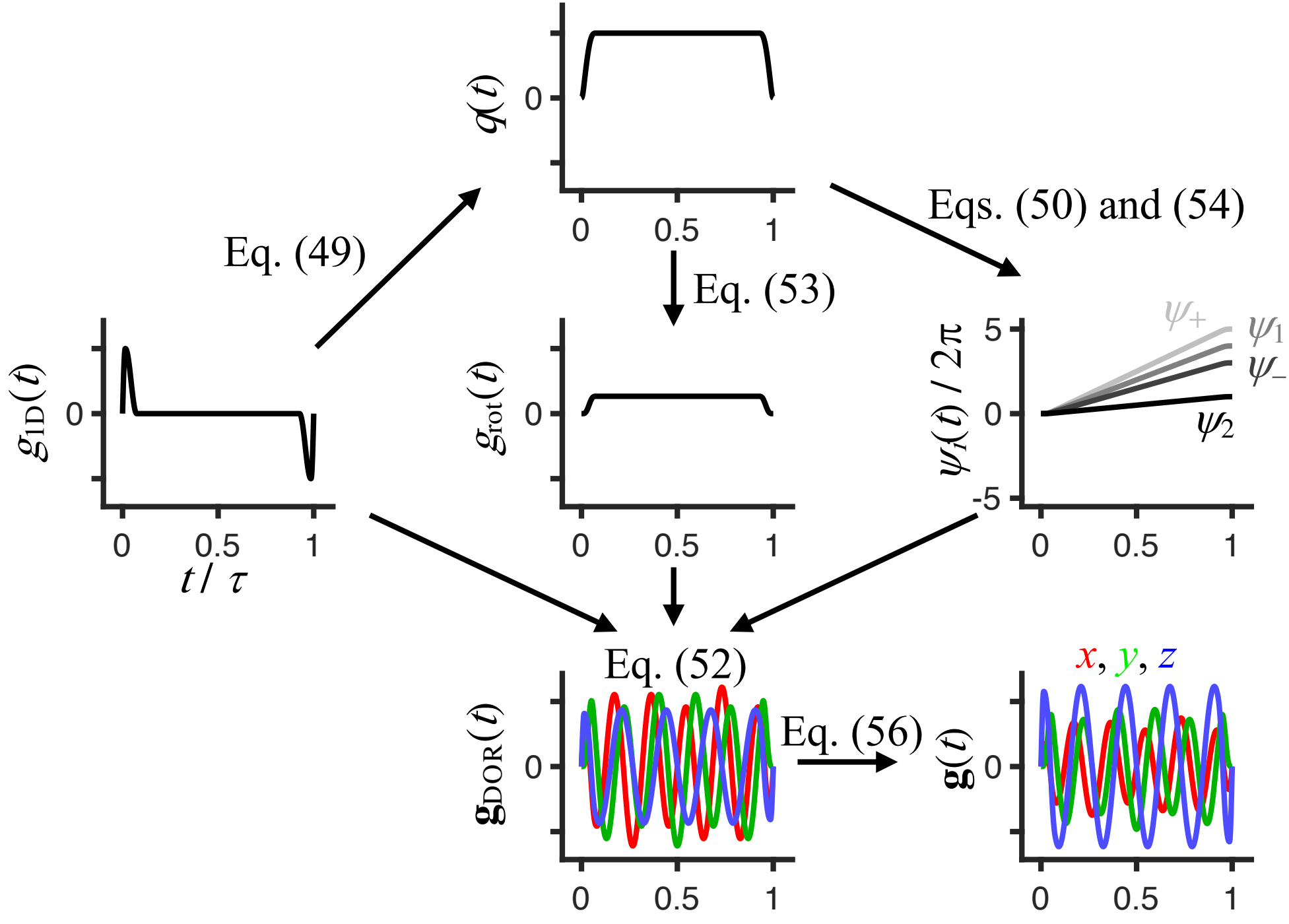
Eq. (49)
Eq. (53)
Eqs. (50) and (54)
Eq. (52)
Eq. (56)
$g_{\mathrm{ID}}(t)$
t / τ
$q(t)$
$g_{\mathrm{rot}}(t)$
$\psi_f(t) / 2\pi$
ψ_+
ψ_1
ψ_-
ψ_2
$\mathbf{g}_{\mathrm{DOR}}(t)$
x, y, z
$\mathbf{g}(t)$