We are grateful to the reviewers for their time and effort in reviewing our manuscript. Since several similar comments were raised by all the reviewers, below is a short response to the main comments of all reviewers:

- Spin-lock profile of ¹H in 99.96% D₂O were acquired and added to the main text.
- The discussion regarding the simulations was extended. In particular, numerical simulations were compared with the first-order Hamiltonian solution.
- We added more simulations and discussion to emphasize that the appearance of rotaryresonance conditions in isotropic samples is not due to the amplitude or width of the
 distribution (either external magnetic field or radio-frequency field irradiation). While the
 amplitude and width of the distribution influence the width of the rotary-resonance
 conditions, the modulation frequency, and the minimum intensity of the spin-lock signal
 at these conditions, the rotary-resonance conditions arise due to the periodic dependence.

Below is a point-by-point response (in blue) to reviewer comments (in black).

Anonymous Referee #1

1) Numerical simulations

The description of the numerical simulations provided in the SI suggests that the authors performed simulations for a single-spin-1/2 system by numerical integration of the Liouville-von Neumann equation. Based on Eq. (S2), both the initial density operator as well as the detection operator correspond to Ix (x magnetization). For simulations taking the spatial rf-field inhomogeneity into account, the Hamiltonian of the system corresponds to a spinlock along the x-axis (Eq. (S3C)) and an orthogonal component along the y-axis that is modulated by the MAS frequency (Eq. (S3B)). This will generate an effective field whose orientation and magnitude will be modulated by the MAS frequency and about which the magnetization will nutate. Due to spatial inhomogeneity of the rf field, the orientation and magnitude of this effective field will vary across the sample space. The authors model the spatial rf-field distribution using distribution functions f_B1 (that models the amplitude distribution along the rotor axis) and f_nu1 (that models the magnitude of the modulated component along the yaxis) and compute the total signal as the weighted average of these distributions (Eq. (S2)). Unfortunately, the functional forms of these distribution functions are not provided (which they should be) and can only be approximated based on Fig. S1. Since no other spin-spin or spin-field interactions are mentioned, it must be assumed that no other interactions are taken into account, which would be in line with an isotropic sample of an isolated nucleus. Moreover, the authors explicitly say that no relaxation is taken into account in the simulations and the effect therefore has to be coherent in nature. However, computing the signal based on this information (which is computationally inexpensive for a single-spin system) does not lead to the same results presented by the authors in Fig. 3 in the main text. I would therefore ask the authors to provide additional information on how the simulations were performed.

We have added the Table S1 to the supplementary information (SI), which summarizes the used weighting factors:

	The Amplitude (in kHz)	The weighting factor
B_0 modulation	0.2(k-1)/V	$2(k-1)/V^2$
k=[1:51]		

B_1 modulation, time- independent l =[1:29]	$\nu_{SL}\left(1-(l-1)\frac{0.05}{M}\right)$	$e^{-\left(1.89\frac{(l-1)}{M}\right)^2} / \left(\sum_{l=1}^{M} e^{-\left(1.89\frac{(l-1)}{M}\right)^2}\right)$
B_1 modulation, time- dependent $k=[1:29]$	$0.1\nu_{SL} \left(1 - e^{-\left(1.26 \frac{(k-1)}{W}\right)^4} \right)$	$e^{-\left(1.26\frac{(k-1)}{W}\right)^4} / \left(\sum_{k=1}^{W} e^{-\left(1.26\frac{(k-1)}{W}\right)^4}\right)$

Table S1 The summary of the amplitudes and the weighting factors for B_0 and B_1 modulations (the simulations are shown in Figures 4 and 5 in the main text). In simulations, M=29, W=29 and V=51.

We have also extended our discussion regarding the simulations and added the first-order Hamiltonian solution, comparing it with the numerical simulations. The following paragraph has been included in SI:

"To understand the origin of the pseudo RRD effect, we start with the simplest case, investigating the behavior of a single on-resonance spin during the rf-field spin-lock (H_{SL}) . The single spin inside the coil may be affected by an additional time-periodic term (H_t) , orthogonal to the applied rf-field spin-lock. For simplicity, we also do not include any relaxation effects.

This additional term can depend on the external magnetic field (B_0 modulation), or the strength of the applied RF-field spin-lock (B_I modulation). In solid samples, it can arise due to anisotropic interactions. The first and second modulations are related to inhomogeneities in the external magnetic field and RF field, respectively. The third could arise in liquid-like samples if there is some degree of alignment and therefore residual anisotropic interactions present. Knowing the exact values of these modulations (and shapes in the case of the distribution) is important when their influence is investigated quantitatively for a specific coil. Our goal here is the qualitative determination of the source of the pseudo RRD effect in the experiments.

In all three cases, the total Hamiltonian for this spin can be described as follows:

 $H_{total} = H_{SL} + H_t = \omega_{SL}I_x + 2\pi \sum_n a_n \cos(n\omega_R t + \phi_n)I_z\widehat{Op},$ *Eqn.* (S1) where $\omega_{SL}=2\pi v_{SL}$. Here, $\widehat{Op}=1$ for a single spin or $\widehat{Op}=2S_z$ for a two-spin system. While for anisotropic interactions, n is 1 or 2, 1,2 for B_0 and B_1 modulations, n may take any integer value.³ This is because these modulations are not purely sinusoidal, there are contributions from overtone frequencies. In the experimental SL profiles (Figures 2 and 3 in the main text), two rotary-resonance conditions are clearly observed. Therefore, in the following discussion, n = 11, 2 will be considered for all three cases.

The simulated SL-signal is defined as follows:

$$S_{SL}(t_{SL}) = Tr \left\{ I_x \widehat{T} e^{-i \int_0^{t_{SL}} dt H_{total}} I_x \widehat{T} e^{i \int_0^{t_{SL}} dt H_{total}} \right\}, \qquad Eqn. (S2)$$

where \hat{T} is a Dyson operator. To simplify Eqn. (S1), the total Hamiltonian is transformed into the tilted rf-field frame:1

$$H_{tot}^{rf} = U_{SL}^{-1} H_{tot}(t) U_{SL} - H_{SL},$$
 Eqn. (S3)

 $H_{tot}^{rf} = U_{SL}^{-1} H_{tot}(t) U_{SL} - H_{SL}, \qquad \qquad Eqn. \ (S3)$ where $U_{SL} = e^{-i\omega_{SL}tI_x}$ is a propagator. The modified Eqn. (S2) in the titled frame is written as follows:

$$S_{SL}(t_{SL}) = Tr \left\{ I_x \hat{T} e^{-i \int_0^{t_{SL}} dt H_{tot}^{rf}} I_x \hat{T} e^{i \int_0^{t_{SL}} dt H_{tot}^{rf}} \right\}, \qquad Eqn. (S4)$$

since the initial and the measured operators (I_x) commute with U_{SL} .

The modified Eqn. (S1) is:

$$H_{tot}^{rf} = 2\pi \sum_{n=1}^{2} a_n \cos(n\omega_R t + \phi_n) \left(I_z \cos(\omega_{SL} t) + I_y \sin(\omega_{SL} t) \right) \widehat{Op},$$
 Eqn. (S5) where \widehat{Op} remains unchanged as it commutes with U_{SL} . The Eqn. (S5) can be rewritten in the following way:

$$H_{tot}^{rf} = Eqn. (S6)$$

$$\pi \sum_{n=1}^{2} a_n \left[\left(cos \left((n\omega_R + \omega_{SL})t + \phi_n \right) + cos \left((n\omega_R - \omega_{SL})t + \phi_n \right) \right) I_z + \left(sin \left((n\omega_R + \omega_{SL})t + \phi_n \right) - sin \left((n\omega_R - \omega_{SL})t + \phi_n \right) \right) I_y \right] \widehat{Op}.$$

We see in Eqn. (S6) both $I_z\widehat{Op}$ and $I_y\widehat{Op}$ operators, which do not commute with the initial and final operators and are cosine or sine modulated. For small an, these terms can be approximated as zero, except for specific values of the spin lock frequency.

Under specific cases, when $k\omega_R - \omega_{SL} = 0$ (k=1 or 2), Eqn. (S6) can be rewritten as:

$$H_{tot}^{rf} = \pi a_k \left[\cos(\phi_n) I_z - \sin(\phi_n) I_y \right] \widehat{Op} + H_{else}^{rf}, \qquad Eqn. (S7)$$

while H_{else}^{rf} is:

$$H_{else}^{rf} = \pi \sum_{n=1}^{2} a_n \left[cos((n+k)\omega_R t + \phi_n) I_z + sin((n+k)\omega_R t + \phi_n) I_y \right] \widehat{Op} \qquad Eqn. (S8)$$

$$+ a_j \left[cos((-1)^{k+1}\omega_R t + \phi_n) I_z - sin((-1)^{k+1}\omega_R t + \phi_n) I_y \right] \widehat{Op},$$

where for the k=1 condition, j=2; and for the k=2 condition j=1. Eqn. (S7) can be further simplified using average Hamiltonian theory, ⁴ considering only the first-order term:

$$T_R H_{tot}^{rf(0)} = \pi T_R a_k \left[\cos(\phi_n) I_z - \sin(\phi_n) I_y \right] \widehat{Op} = e^{-i\phi_n I_x} \frac{\pi a_k}{\nu_R} I_z \widehat{Op} e^{i\phi_n I_x}, \qquad Eqn. (S9)$$

where the average, H_{tot}^{rf} (0), is taken over one rotor period ($T_R = \frac{1}{\nu_R} = \frac{2\pi}{\omega_R}$). Regardless of the explicit form of the \widehat{Op} operator, the measured spin-lock signal, according to Eqns. (S4) and (S9) is as follows:

$$S_{SL}(t_{SL} = N_{SL}T_R) \approx cos\left(\pi \frac{a_k}{v_R}N_{SL}\right),$$
 Eqn. (S10)

since $e^{-i\phi_n l_x}$ commutes with the initial and final operators. For dipolar interactions, Eqn. (S10) should be modified to account for all orientations:

$$S_{SL}(t_{SL} = N_{SL}T_R) \approx \int d\Omega \cos\left(\pi \frac{a_k}{v_R} N_{SL}\right),$$
 Eqn. (S11)

The integration over orientation (Ω) indicates the powder averaging with Euler angles, (α, β, γ) .¹

Figure S1 compares numerical (solid lines) and FOH curves (stars) under the rotary-resonance conditions $v_{SL} = v_R$ (Figures S1A-C) and $v_{SL} = 2v_R$ (Figures S1D-F) and different α_k values, related either to B_0 modulation (Figures S1A and D), dipolar interaction (two-spin system, Figure S1B and E) or B_1 modulation (Figures S1C and F). These figures show full agreement between numerical and FOH curves. In all three cases, the changes in α_k values affect the modulation frequency of the spin-lock signal.

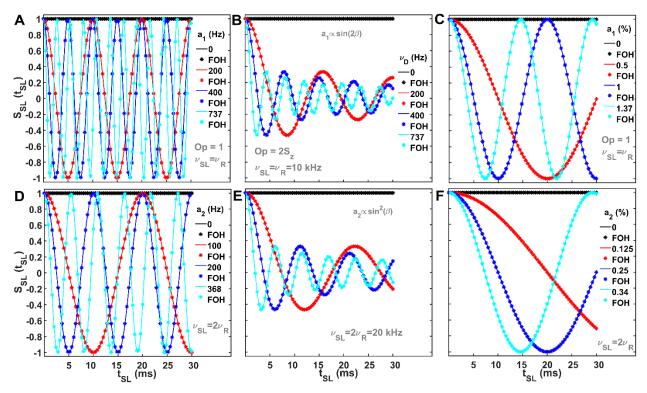


Figure S1 Numerical spin-lock (solid) and FOH (stars, Eqns. (S10) and (S11)) signals were simulated with different values of B_0 modulation (a single spin, A and D), dipolar coupling values (two spin-system, B and E) and B_1 modulation (a single spin, C and F) at rotary-resonance conditions, where $v_{SL} = v_R$ (A-C) and $v_{SL} = 2v_R$ (D-F). In (A) and (D), $a_2 = 0.5a_1$ with a_1 : 0 - black; 200 Hz – red; 400 Hz – blue and 737 Hz – cyan. In (B) and (D), $a_1 = \frac{v_D}{\sqrt{2}}\sin(2\beta)$ and $a_2 = -\frac{v_D}{2}\sin^2(\beta)$ with dipolar coupling values v_D of: 0 - black; 200 Hz – red; 400 Hz – blue and 737 Hz – cyan. In (C) and (F), $a_2 = 0.25a_1$ with a_1 : 0 - black; 0.5% – red; 1% – blue and 1.37% – cyan. All simulations performed at 10 kHz MAS.

Dependence of the numerical (solid lines) and FOH curves (stars) on MAS rate is shown in Figure S2 under the conditions $a_1 = 2a_2 = 0.2$ kHz of B_0 modulation (Figures S2 A and D), $v_D = 0.2$ kHz of dipolar interaction (Figures S2 B and E) and $a_1 = 4a_2 = 1$ % of nominal B_1 (Figures S2 C and F), for both rotary-resonance conditions ($v_{SL} = v_R$ and $v_{SL} = 2v_R$). Only for B_1 modulation (Figures S2 C and F) does the change of MAS rate affect the modulation frequency. This is a simple consequence of B_1 modulation amplitude scaling up with B_1 .

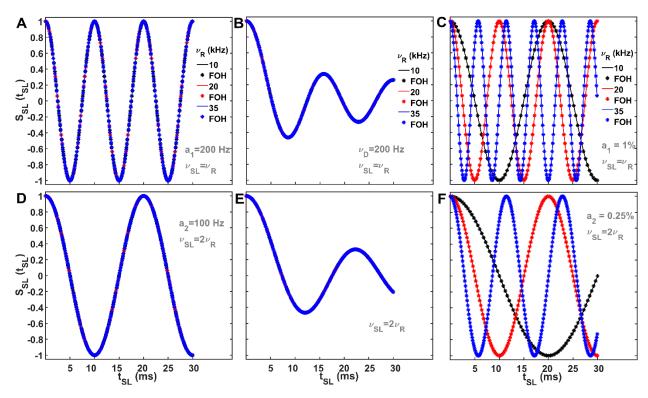


Figure S2 Numerical spin-lock (solid) and FOH (stars, Eqns. (S10) and (S11)) signals were simulated for B_0 modulation (a single spin, A and D), dipolar coupling values (two spin-system, B and E) and B_1 modulation (a single spin, C and F) at rotary-resonance conditions, where $v_{SL} = v_R$ (A-C) and $v_{SL} = 2v_R$ (D-F) under different v_R : 10 kHz – black; 20 kHz – red; and 35 kHz – blue.

While Figure S2 shows spin-lock signals only at rotary-resonance conditions, Figure S3 presents numerical SL profiles for spin-lock strengths between 1 and 44 kHz under three different MAS rates: 10 kHz (A-C), 20 kHz (D-F) and 35 kHz (G-I) for B_0 modulation (A, D and G), dipolar interaction (B, E and H) and B_0 modulation (C, E and I). The same conclusions as in Figure S2 are observed: for B_0 modulation (A, D and G) and dipolar interaction (B, E and H), the changes in MAS do not affect the modulation frequency, while for B_1 modulation (C, F and I), this is not the case (marked in gray in Figure S3). Additionally, the profiles show that the rotary-resonance conditions are narrow: a deviation of only 100 Hz from these conditions almost completely removes the influence of the time-dependent term on the spin-lock signal in all figures.

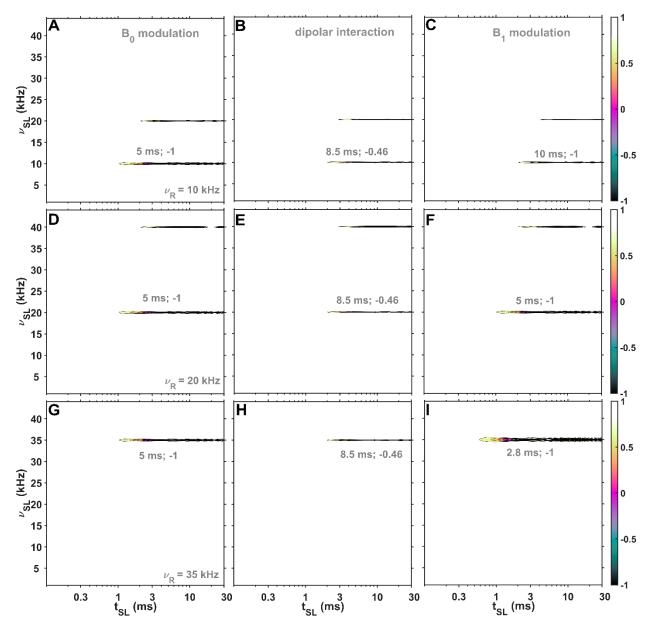


Figure S3 Numerical SL profiles showing the influence of time dependence introduced via B_0 modulation ($a_1 = 0.5a_2 = 100$ Hz, A, D and G), dipolar interaction ($v_D = 200$ Hz, B, E and H) and B_1 modulation ($a_1 = 0.25a_2 = 0.01v_{SL}$, C, F and I). The simulated signal is shown as a function of the rf-field strength (v_{SL} , axis y) and mixing time (t_{SL} , axis x) of the SL under three different MAS rates: 10 kHz (A-C), 20 kHz (D-F) and 35 kHz (G-I). The values in gray represent the coordinates of the first minimum in the profiles. No phenomenological relaxation was included in the simulations.

In addition to time dependence induced by B_1 inhomogeneity, there is also time independent inhomogeneity, $^{5-10}$ which is most clearly seen along the axis of the rotor. Including this in the simulation broadens the rotary-resonance conditions. With addition of a time-independent term, parallel to the applied spin lock Hamiltonian becomes:

$$H_{SL} = 2\pi (v_{SL}I_x - \Delta_{B_1}v_{SL}I_x) = 2\pi v_{SL}(1 - \Delta_{B_1})I_x,$$
 Eqn. (S12)

where Δ_{B_1} represent the inhomogeneity factor for a given position in the sample. Experimentally, the reason of the appearance of this term is due to the fact that a solenoidal coil produces a higher rf-field at the center, as compared with the edges. Rather than explicitly averaging over the sample volume, we consider an approximate linear distribution of spin-lock signal. The average signal is then the sum of M signals with $v_{SL,l} = v_{SL} \left(1 - (l-1) \frac{\Delta_{B_1}}{M}\right) (l=1,...,M)$ and normalized with a Gaussian weighting factor, 5,6,8,11 $g_{B_1,l}$:

$$S_{SL}(t_{SL}) = \sum_{l=1}^{M} g_{B_1,l} Tr \left\{ I_x \hat{T} e^{-i \int_0^{t_{SL}} dt H_{total,l}} I_x \hat{T} e^{i \int_0^{t_{SL}} dt H_{total,l}} \right\},$$
 Eqn. (S13) where \hat{T} is a Dyson operator and $g_{B_1,l} = e^{-\left(1.89 \frac{(l-1)}{M}\right)^2} / \left(\sum_{l=1}^{M} e^{-\left(1.89 \frac{(l-1)}{M}\right)^2}\right).$

The total Hamiltonian, $H_{total,k}$, is defined as follows:

$$H_{total,l} = \omega_{SL} \left(1 - (l-1) \frac{\Delta_{B_1}}{M} \right) I_x + 2\pi \sum_{n=1}^2 a_n \cos(n\omega_R t + \phi_n) I_z \widehat{Op}.$$
 Eqn. (S14)

In the following simulations, Δ_{B_1} =0.05 (5% with respect to applied v_{SL}). While the value of Δ_{B_1} as well as the weighting factor can be different from coil to coil, this term is not the source of the appearance rotary-resonance conditions. However, this term broadens the rotary-resonance conditions and alters the positions and values of the first minimum signal intensities, as shown in Figure S4.

As in the previous simulations, for B_0 modulation (A, D and G) and dipolar interaction (B, E and H), changes in MAS do not affect the modulation frequency, while for B_1 modulation (C, F and I), this is not the case. Additionally, for both B_0 modulation and dipolar interaction, the intensities at the first minima show a dependence on MAS rate, while for B_1 modulation, they do not (marked in gray in Figure S4). This differing dependence on MAS rate for B_1 modulation versus B_0 modulation and dipolar interaction could indicate which effect plays a major role in rotary-resonance condition experiments for isotropic samples. Since the rotary-resonance effect is observed for 1H spins in 99.96% D_2O (Figure 3A-B in the revised main text), the dipolar interaction was not included in simulations in the main text.

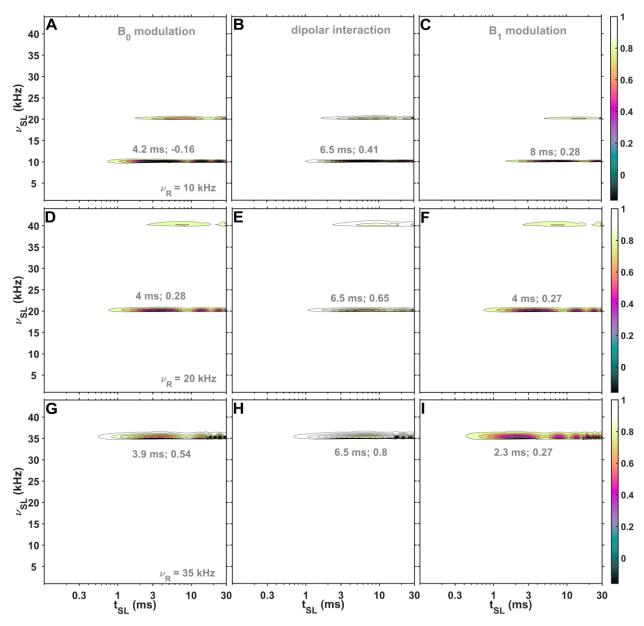


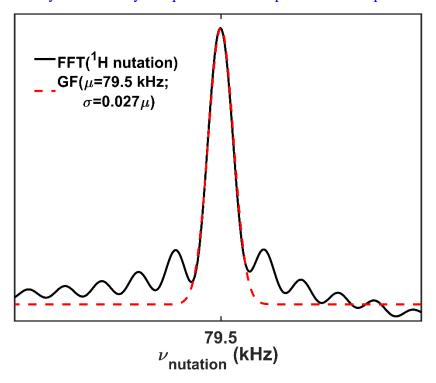
Figure S4 Numerical SL profiles with an additional time-independent term ($\Delta_{B_1} = 0.05$, Eqns. S12-S14) showing the influence of time dependence introduced via B_0 modulation ($a_1 = 0.5a_2 = 100$ Hz, A, D and G), dipolar interaction ($v_D = 200$ Hz, B, E and H) and B_1 modulation ($a_1 = 0.25a_2 = 0.01v_{SL}$, C, F and I). The simulated signal is shown as a function of the rf-field strength (v_{SL} , axis y) and mixing time (t_{SL} , axis x) of the SL under three different MAS rates: 10 kHz (A-C), 20 kHz (D-F) and 35 kHz (G-I). The values in gray represent the coordinates of the first minimum in the profiles. No phenomenological relaxation was included in the simulations."

2) Model for the rf inhomogeneity

In my opinion, the model used for the spatial distribution of the rf-field in a solenoid coil is not appropriate due to the following issues: - The authors assume an amplitude deviation from the nominal spinlock amplitude of only 0-5% (Eq. (S3C)). However, both simulated (e.g. Tosner et. al. 2017) and measured (e.g. Gupta et. al. 2015) rf-field distributions of common MAS NMR probes suggest that the field drops to approximately 50% at the edges of the sample space. Since there is no mention of spatial sample restriction to the central part of the rotor, the chosen amplitude distribution is not appropriate. -

For a maximum deviation of the spinlock amplitude of 5% the signal weighting function given in Fig. S1C is not appropriate. According to the reciprocity theorem (e.g. Hoult 1976), the induced signal is directly related to the B1 field of the receiving coil at a given position in the sample space. A deviation from the nominal field by 5% should therefore not lead to a weighing of the signal with a factor of close to zero as is shown in Fig. S1C. - The orthogonal component (Eq. (S3B)) occurs due to the MAS modulation of the phase of the rf irradiation which is known to be strongest at the edges of the sample space (e.g. Tosner 2017). Since the spinlock amplitude is also significantly lower than the nominal spinlock amplitude in these parts of the sample, the rotary resonance condition is no longer fulfilled in these parts of the sample and the coil sensitivity is significantly lower. However, the model implemented by the authors uses the same magnitude of the modulation for all values of f_B1. Since simulated realistic rf-field distributions can be found in the literature (Tosner et. al. 2017), I would suggest that the authors perform their simulations using such a distribution instead of this crude model that

The following figure depicts the Fourier Transform of the nutation curve (black), which was acquired using a series of 1D 1H experiments in 99.96% D_2O as a function of the single pulse length, ranging from 0.5 μ s to 160 μ s in 0.5 μ s steps. The Gaussian function (red dashed line) with a standard deviation of 0.027μ (μ = 79.5 kHz) shows that this distribution can approximately be considered Gaussian (as reported in previous works), $^{4-6}$ and that the 5% maximum deviation used in the simulations approximates the actual distribution. The exact distribution would only be necessary for quantitative comparison with experiments.



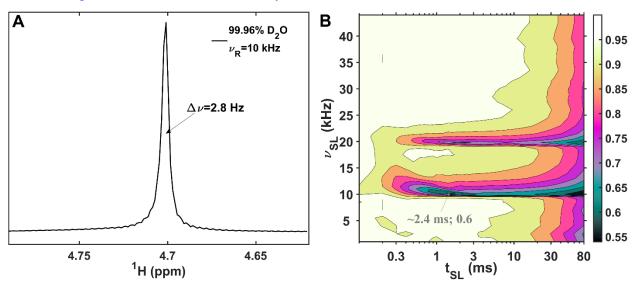
Fast Fourier Transform (FFT) of 1D 1H signal as a function of the length of single proton pulse (black) and comparison with a Gaussian function (red dashed). The sample was 99.96% D₂O. For FFT, MATLAB software was used. The experiments were performed at 10 kHz MAS.

3) Isotropic sample

The experimental results presented in the paper stem from measurements of a polybutadiene rubber sample as well as a polyethylene glycol sample. Although these sample exhibit "liquidlike" spectra, they

both correspond to large polymer systems, where partial alignment might lead to residual anisotropic dipolar interactions that will be recoupled for irradiation at a rotary resonance condition. The comparison of experimental spectra of the rubber sample with and without MAS (Fig. S4A) shows that the static spectrum is significantly broader than the one under MAS. This line broadening can either be attributed to residual anisotropic interactions or susceptibility effects and raises the question if either of the two are re-introduced by irradiating at the rotary resonance condition which would lead to signal decay. The authors attribute the observed signal decay solely to the modulation of the rf-field due to the rf inhomogeneity, based on numerical simulations of a single-spin system. This raises the question why the authors didn't choose to demonstrate the effect using a truly isotropic system (such as, for example, the residual H2O line in D2O) that would correspond more closely to what is simulated.

The suggested experiments were performed and included into the revised version of the article as Figure 3. We also observed rotary-resonance conditions for ¹H in 99.96% D₂O.



 1 H in 99.96% D₂O experiments. (A) 1D spectrum recorded at 10 kHz MAS. (B) 1 H signal is shown as a functions of the rf-field strength (ν_{SL} , y-axis) and mixing time (t_{SL} , x-axis) of the SL pulse. The sample contained Cu²⁺ ethylenediaminetetraacetic acid disodium salt (5 mM) to accelerate the acquisition.

4) Additional Remarks:

- The different positions of the minima of the signal intensity in the experimental and simulation results is never discussed.

The positions of the signal intensity minima in the experimental and simulated SL profiles are similar. In the experimental profiles, we observe minima at approximately 2.4 ms, 2.4 ms, 1 ms, and 0.4 ms for 10 kHz, 10 kHz half-windowed, 25 kHz, and 35 kHz MAS, respectively. In the simulations, these values are 1.8 ms, 1.8 ms, 0.9 ms, and 0.5 ms. In the experiments, the minima positions are broader than in the simulations. For example, for 10 kHz MAS (Figure 2A), the minima can be identified between 1.8 ms and 3 ms, where similar minima intensities are observed. The intensity values at these minima points depend on the amplitude of the B_1 -modulated term. Since our goal is a qualitative comparison of the experimental and simulated SL profiles, we do not expect a full agreement between them.

- I think the authors should put more emphasis on distinguishing coherent from incoherent effects that lead to signal decay. Since the experimental data clearly shows an oscillating behavior and no stochastic

processes (e.g. molecular motion) are taken into account in the numerical simulations that are used to explain the observed phenomenon, the underlying mechanism has to be coherent. However, the abstract of the paper suggests "maxima in relaxation rates" (p. 1, l. 15) and "enhanced transverse relaxation" (p.1, l.10), which makes it sound like the observed signal decay is due to incoherent line broadening.

We corrected the mentioned sentence:

"A drastic reduction in spin-lock signal intensities is observed when the spin-lock frequency matches one or two times the MAS rate. Under these conditions, the spin-lock signal decays at a much higher rate, and oscillations of the signal are observed, consistent with a coherent origin of the effect."

A comparison with the first-order Hamiltonian solution (please refer to the response to point #1) emphasizes that we are considering only coherent effects.

- In the experimental data, it is not clear what the "signal intensity" is that is plotted. Is this the integrated intensity or the maximum peak intensity?

The peak maximum was used to plot all SL profiles, except for one in Figure S4 of the supplementary information (first version), where both the integrated intensities and peak intensities were measured from the same experimental data. We have added clarification to the figure captions.

- In the text and the figure legends the spinlock amplitude is referred to as nu_SL whereas in the axis of the figure it is denoted by nu_RF. The nomenclature should be consistent to avoid confusion.

Corrected.

- The discussion of other reports of the effects of the MAS modulation of the rf field due to the spatial inhomogeneity is rather minimalistic. The authors may want to include the seminal works by Tekely and Goldman for example. o Goldman, M. and Tekely, P.: Effect of radial RF field on MAS spec tra, CR Acad. Sci. II C, 4, 795–800, 2001. o Tekely, P. and Goldman, M.: Radial-field sidebands in MAS, J. Magn. Reson., 148, 135–141, 2001.

We have added the citation of the mentioned works with the following discussion. In addition we cite Aebischer et al. MR 2021, in which radial spatial inhomogeneity is investigated.

"Some other works regarding the effects of radial RF field on MAS spectra have been reported previously, 3,9,12,13 where the appearance of sidebands due to time-dependent rf-field inhomogeneity was theoretically explored and experimentally demonstrated. Particularly, Aebischer et al. investigated the influence of time-dependent modulations of the rf-field amplitude and phase on the performance of selected solid-state NMR experiments. The influence of both amplitude and phase modulations was observed in samples with non-vanishing anisotropic interactions. These modulations did not significantly affect most recoupling sequences, with the exception of double quantum C-symmetry sequences. ¹⁴ Consistent with the matching conditions identified in this study, Aebisher et al. revealed significant amplitudes at v_R and $2v_R$ in nutation spectra.

Referee #2: Zdeněk Tošner

This contribution reports about a surprising observation that T1rho of liquid-like samples shows enhanced relaxation at rotary resonance conditions known from rotating solids. It is not expected for samples where dipolar interactions are completely averaged by fast motions. It is argued that this phenomenon arises when liquid-like samples are rotated in a spatially inhomogeneous radiofrequency field of solenoid coils. Consequently, similar effect could be expected for solids, changing thus interpretation of rotary resonance relaxation dispersion experiments.

While I understand urgency of this report, I would appreciate a more thorough study. Here are my concerns:

• Rubber and polymer samples are liquid-like, but not quite typical liquids. There still might be nonzero residual dipolar couplings. MAS imposes centrifugal forces and polymer particles may become "solidified" on the rotor walls – can it be excluded?

We also observed rotary-resonance conditions for ¹H in 99.96% D₂O. See also the response to point #3 from Reviewer 1.

• If the explanation is solely time-variable rf field, it can be modelled in liquid state probes without sample spinning by applying shaped pulses. These experiments would then be very convincing experimental proof of the phenomenon.

We have simulated the effect as fluctuations in the z-component of the rf field generated by a solenoid tilted at the magic angle. (The y-component can also be significant.) The situation is quite different in a solution probe, where generation of a z-component would not be achievable with the coil. Yes, a y-component could be generated with a digitized shape pulse. However, this artificial setup would not add much to what is already evident from the simulations, in our view. It would not tell us whether B_0 or B_1 fields are more significant in the MAS rotor.

Quality of the supporting material is not sufficient to reproduce the simulations. There are many typos and unclear nomenclature. For example, what is integral of "df dg f(x) g(B1)" (what is the "df" element?) The time-variable rf Hamiltonians are defined using a sum over n (n=1, 2) of cos(\omega_R t) – there is no "n" under the sum. A graph of these Hamiltonians would help. No reasoning is given for f(\nu_1) being biquadrate exponential distribution function, etc...

For simulation details, please refer to the response to point #1 from Reviewer 1. We thank the reviewer for pointing out the missing 'n' in Eqn. (S3). We added the sentence regarding the biquadrate exponential distribution function:

"The bi-quadrate exponential distribution function does not represent the real distribution of the time-dependent B_1 modulation; it simply provides non-linear sampling, different from the time-independent term."

 I miss more detailed simulation study on the extent of rf modulations introducing enhanced relaxation. I mean some assessment what the amplitude of rf modulations must be, perhaps in relation to the nominal rf amplitude, to observe the phenomenon? RF field modulations within an MAS rotor are of different amplitude, depending on the position along the coil axis as well as on the radial distance... In simulations, 10% amplitude modulations are assumed regardless of the position.

We agree that more a detailed simulation study is important, when this effect is quantitatively investigated for a specific coil. However, it is beyond the scope of this article, as our goal is to illustrate the effect. Our approach does not explicitly consider radial distance. However the inclusion of a distribution of amplitudes for the modulation does approximate the situation in the sample.

 Our detailed calculation of rf field in solenoids show MAS induced variations on the frequency of \omega_R. Where exactly is the origin of the second recoupling condition at two times \omega_R? It comes naturally from MAS modulations of the residual dipolar couplings (rank-2 tensors) but rf field is modulated at just a single frequency...

The amplitude and phase profiles in the previously reported work⁹ are not purely sinusoidal. This makes sense when considering a location in the rotor that passes close to a coil turn over a small angular distance, and is otherwise far from that coil turn, and is particularly noticeable towards the edge of the coil. Since the wave is not purely sinusoidal, there are contributions from overtone frequencies (see e.g. sawtooth or triangular waves, in which many overtones are present). We kept only n=1 and n=2, since these are clear experimentally. However, rotary-resonance conditions with n>2 may also be observed. n=3 appears to show up very weakly in the new D_2O data, in which we sampled more carefully around this condition.

Anonymous Referee #3

• Would one expect such behavior for water or generally for molecules tumbling in the picosecond time scale, true "liquid-like," for example, glycine in water? Is there any specific reason for restricting the study to PEG and rubber? The molecular weight of the PEG used in the study is unclear. One would also expect high molecular weight PEGs to show anisotropic molecular tumbling or sediment on the rotor wall. Perhaps data on molecules showing averaging of dipolar interactions would be comprehensive proof.

We also observed pseudo rotary-resonance conditions for ¹H in 99.96% D₂O. See also the response to point #3 from Reviewer 1.

 Perhaps it might be helpful to measure the rotation correlation timescale of the PEG sample instead of making a hand-waving argument.

Since we see the effect in the residual water in D_2O , this should not be necessary (the effect is not dependent on the change of rotational correlation times between PEG and water).

 The decay of magnetization appears (not sure) to indicate minima/oscillations. Is this a feature of incoherent effects?

This is a characteristic of the coherence effects. We corrected the sentences that previously mistakenly implied incoherent effects were being considered.

• Is there any special reason for using different decoupling schemes at different MAS frequencies, especially if the claim is that the samples are "solution-like"? It's probably not a relevant point, but it's just curiosity.

The same decoupling scheme was used at different MAS frequencies. However, different decoupling schemes were used for different probes: WALTZ16 15 for the 1.3 mm and SW_f-TPPM 16 for the 4 mm. There was no particular reason for this; it is just the result of setting up the sequences for the different probes, and selecting a decoupling sequence.

 Comparing Figure 2 and Figure 4, despite using smaller rf inhomogeneity in simulations compared to typically reported on MAS probes, the magnetization decays substantially faster in simulations. What is the experimental rf inhomogeneity of the rf field?

Please refer to the response to point #4 from Reviewer 1. The key feature of the inhomogeneity has to do with the oscillatory part, which is not easy to characterize experimentally.

The simulation details are sketchy, especially the terms in Eq S2.

Please refer to the response to point #1 from Reviewer 1.

• By naively looking at Equations S3A and S3B, it's not so apparent why the simulations differ except for the weighting factors, which have a different slope and magnitude. In Eq S3, "n is missing" in the cosine term. Is there a justification for summing over n=1,2, or is it motivated by experimental observations?

We thank the reviewer for pointing out the missing 'n' in Eqn. (S3). The summing over n=1, 2 was motivated by experimental observation, despite the possibility for higher values of n to contribute.

• Is it sufficient to consider inhomogeneity distribution along one axis in both scenarios? Why should that be the case?

We have chosen not to explicitly simulate over the spatial axes of the sample, but rather provide a qualitative simulation. Quantitative agreement would require a more detailed simulation, and also taking precautions that there is little to no air bubble present after sample loading, otherwise the very center of the rotor will not be filled with sample. (In case the reviewer refers to spin axes, in revised version we show simulations, in which we consider B_0 and B_1 modulations along the same spin axis (I_z) .)

Minor points

Page 3, line 9 chose

We are not sure what the reviewer means. With the addition of the water sample, this text now reads:

"The same behavior is observed for a polyethylene glycol solution at 10 kHz MAS and for residual protons in liquid deuterium oxide.

We chose these samples since the polybutadiene rubber displays liquid-like spectra but does not undergo translational diffusion due to the elastomeric properties of a cross-linked polymer. On the other hand, since the polybutadiene is an elastomer and therefore may not undergo perfect isotropic averaging, we also recorded data for a polyethylene glycol solution and liquid water."

Different figures have different labels for the rf axis.

Corrected.

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